

Zeros, chaotic ratios and the computational complexity of approximating the independence polynomial

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Very short summary

$$\begin{aligned} & \overline{\{\lambda \in \mathbb{C} : Z_G(\lambda) = 0 \text{ for some } G \in \mathcal{G}_\Delta\}} \\ & = \\ & \{\lambda_0 \in \mathbb{C} \mid \{\lambda \mapsto R_{G,v}(\lambda) \mid (G, v) \in \mathcal{G}_\Delta\} \text{ is not locally normal at } \lambda_0\} \\ & = \\ & \overline{\{\lambda \in \mathbb{C} \mid \{R_{G,v}(\lambda) \mid (G, v) \in \mathcal{G}_\Delta\} \text{ is dense in } \mathbb{C}\}} \\ & \subseteq \\ & \overline{\{\lambda \in \mathbb{Q}[i] : \text{approximating } Z_G(\lambda) \text{ is } \#P\text{-hard}\}} \end{aligned}$$

Definition

Let $G = (V, E)$ a finite graph. A subset $I \subseteq V$ is called an **independent set** if there are no edges between vertices in I . Denote $\mathcal{I}(G)$ the set of independent sets of G .

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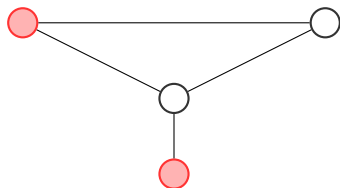


Figure: Independent set of size 2

Independence polynomial

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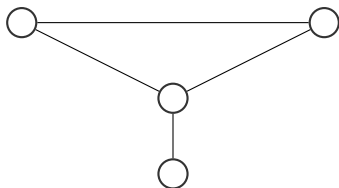
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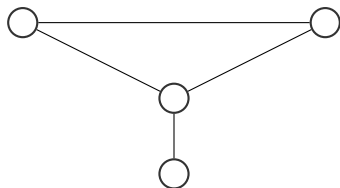


Figure: Independence polynomial $1 + 4\lambda + 2\lambda^2$.

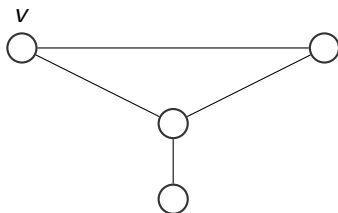


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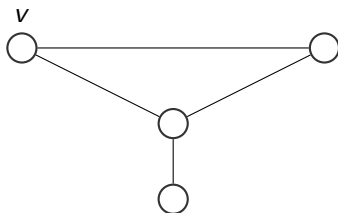


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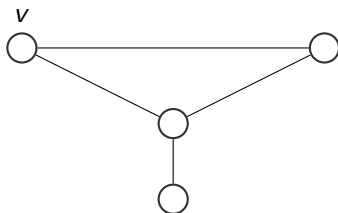


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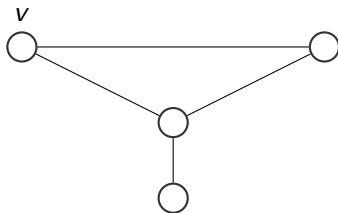


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Remark

We have $Z_G(\lambda) = Z_{G,v}^{in}(\lambda) + Z_{G,v}^{out}(\lambda)$.

Definition

Let $G = (V, E)$ a graph, and $v \in V$ a vertex. We define the rational function

$$R_{G,v}(\lambda) = \frac{Z_{G,v}^{in}(\lambda)}{Z_{G,v}^{out}(\lambda)}.$$

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Remark

Note that if $R_{G,v}(\lambda) = -1$, then we have $Z_{G,v}^{in}(\lambda) = -Z_{G,v}^{out}(\lambda)$ and thus $0 = Z_{G,v}^{in}(\lambda) + Z_{G,v}^{out}(\lambda) = Z_G(\lambda)$.

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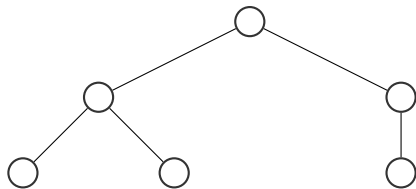
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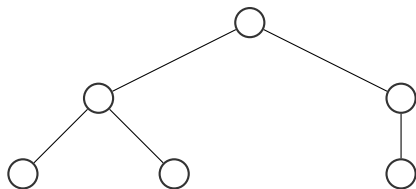
Remark

If we define $f_\lambda(z) = \frac{\lambda}{1+z}$, we see the ratio of an edge is f_λ applied to the ratio of a point.

Trees instead of graphs



Trees instead of graphs



The following result due to Bencs [Ben18], building on Weitz [Wei06].

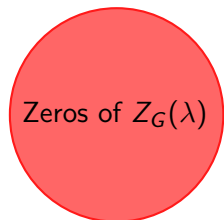
Theorem

Let $(G, v) \in \mathcal{G}_\Delta$ be a rooted connected graph. Then there is a rooted tree $(T, u) \in \mathcal{G}_\Delta$ with $\deg_T(u) = \deg_G(v)$ such that

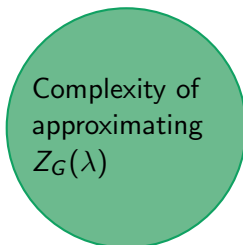
- (i) Z_G divides Z_T ,
- (ii) $R_{G,v} = R_{T,u}$.

Zeros, chaotic ratios and approximation

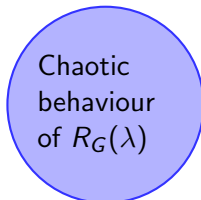
Statistical physics



Computer Science



=



Complex dynamics

Zeros and approximation

Notation

We denote

$$\mathcal{Z}_\Delta = \{\lambda \in \mathbb{C} : Z_G(\lambda) = 0 \text{ for some } G \in \mathcal{G}_\Delta\}.$$

We call $\overline{\mathcal{Z}_\Delta}$ the **zero-locus**.

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Remark

Suppose U is a simply connected open set containing 0 such that $\mathcal{Z}_\Delta \cap U = \emptyset$. Then for each $\lambda \in U$ there exist a polynomial time algorithm to approximate $Z_G(\lambda)$ for each $G \in \mathcal{G}_\Delta$ by Patel and Regts [PR17].

Normal Family

Let \mathcal{F} a family of rational maps $f : \hat{\mathbb{C}} \rightarrow \hat{\mathbb{C}}$.

Definition

For an open $U \subseteq \hat{\mathbb{C}}$ the family \mathcal{F} is **normal on U** if each sequence $\{f_n\}_{n \geq 0} \subseteq \mathcal{F}$ has a subsequence that converges to a holomorphic $g : U \rightarrow \hat{\mathbb{C}}$, uniformly on compact $K \subseteq U$.

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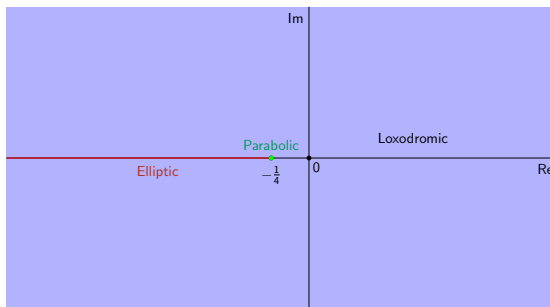
We say a parameter λ_0 is **active** for \mathcal{F} if for any open neighborhood of λ_0 the family \mathcal{F} is not a normal family. The set of all active parameters is called **the activity-locus of \mathcal{F}** .

Example Normality

Recall the map $f_\lambda(z) = \frac{\lambda}{1+z}$. We will determine when the family $\{\lambda \mapsto f_\lambda^n(0)\}$ is normal.

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Elliptic $z \mapsto e^{i\theta} \cdot z$

Parabolic $z \mapsto z + 1$

Loxodromic
 $z \mapsto \xi \cdot z$ for
some $\xi \in \mathbb{C}^*$
with $|\xi| < 1$

Definition

We define the **activity-locus** \mathcal{A}_Δ to be the activity-locus of the family

$$\{\lambda \mapsto R_{G,v}(\lambda) : G \in \mathcal{G}_\Delta \text{ and } v \in V(G)\}.$$

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If the set

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is dense in $\hat{\mathbb{C}}$, we say λ_0 is a **density parameter**. We denote \mathcal{D}_Δ for the set of density parameters and define the **density-locus** to be the closure of \mathcal{D}_Δ .

Definition

We informally define the $\#\mathcal{P}$ -locus as the closure of the collection of λ for which approximating $Z_G(\lambda)$ is $\#\mathcal{P}$ -hard for $G \in \mathcal{G}_\Delta$.

Main theorem

Definition

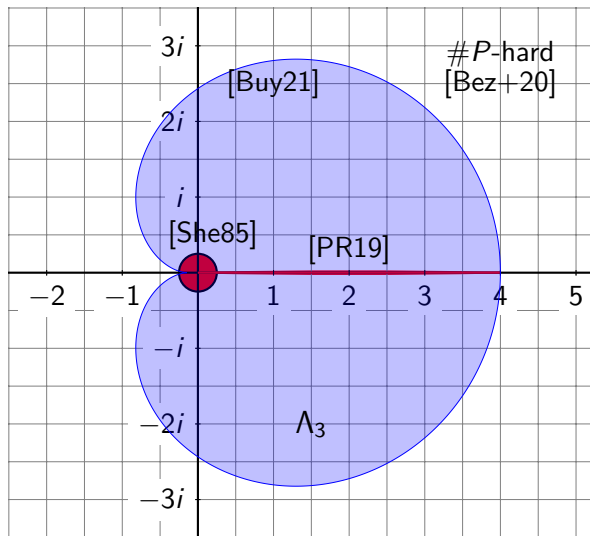
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Main Theorem

For any integer $\Delta \geq 3$ the zero-locus, the activity-locus and the density-locus are equal and contained in the $\#\mathcal{P}$ -locus. In other words:

$$\overline{\mathcal{Z}_\Delta} = \mathcal{A}_\Delta = \overline{\mathcal{D}_\Delta} \subseteq \overline{\#\mathcal{P}_\Delta}.$$

Related results



A useful lemma

Lemma

Let $\lambda \in \mathbb{C} \setminus \{0\}$. If there exists a rooted graph $(G, v) \in \mathcal{G}_\Delta$ for which $R_{G,v}(\lambda) \in \{-1, 0, \infty\}$, then there exists a graph H of maximum degree at most Δ for which $Z_H(\lambda) = 0$.

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$$\text{Now look at } \frac{\lambda \cdot Z_{G-N[v]}(\lambda)}{Z_{G-v}(\lambda)}$$



Active parameters have zeros nearby

Corollary

For all $\Delta \geq 2$ the activity-locus is contained in the zero-locus, i.e. $\mathcal{A}_\Delta \subseteq \overline{\mathcal{Z}_\Delta}$.

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Montel's theorem

Let \mathcal{F} a family of holomorphic functions $f : U \rightarrow \hat{\mathbb{C}}$ for which there are three distinct values that each $f \in \mathcal{F}$ omits. Then \mathcal{F} is normal on S .



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You can show that for $\lambda \in B_\Delta$, the family

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Lemma

Let $\Delta \geq 2$ be an integer. Then B_Δ is disjoint from the activity-locus, the density-locus and the zero-locus, so

$$B_\Delta \cap \mathcal{A}_\Delta = B_\Delta \cap \overline{\mathcal{D}_\Delta} = B_\Delta \cap \overline{\mathcal{Z}_\Delta} = \emptyset.$$

Activity locus for paths

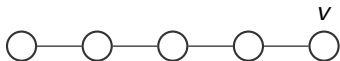


Figure: A path with root v in an endpoint

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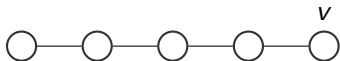


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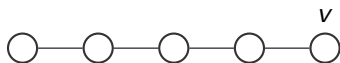


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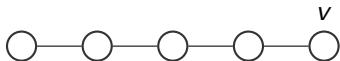


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Corollary

We have for each $\Delta \geq 2$ that

$$(-\infty, -\frac{1}{4}] \subseteq \mathcal{A}_\Delta$$

Lemma

Let $\lambda \in \mathbb{C}$ and $G \in \mathcal{G}_\Delta$ with $Z_G(\lambda) = 0$. Then there is a rooted tree (T, u) with $\deg(u) = 1$ and $R_{T,u}(\lambda) = -1$.

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Then let u a leaf of T , we have $0 = Z_{T,u}^{out}(\lambda) + Z_{T,u}^{in}(\lambda)$

Note that $Z_{T,u}^{out}(\lambda) = Z_{T-u}(\lambda) \neq 0$, so $R_{T,u}(\lambda) = -1$



Zeros imply activity

Proposition

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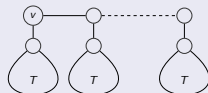
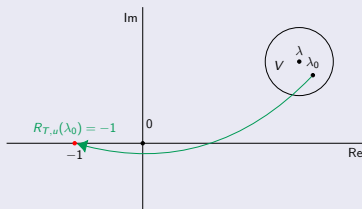
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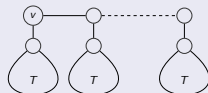
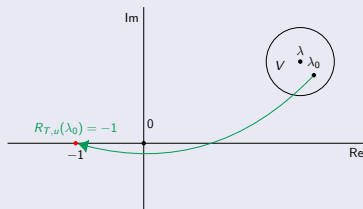


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Proof.



Denote the tree on the right as (T_n, v) and the rooted path (P_n, v_n) . Then

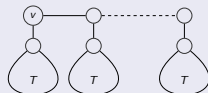
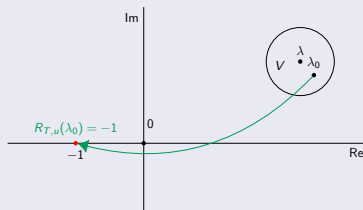
$$R_{T_n, v} = R_{P_n, v_n} \circ R_{T, u}.$$

Zeros imply activity

Proposition

Let $\Delta \geq 2$. Then $\overline{\mathcal{Z}_\Delta} \subseteq \mathcal{A}_\Delta$.

Proof.



Denote the tree on the right as (T_n, v) and the rooted path (P_n, v_n) . Then

$$R_{T_n, v} = R_{P_n, v_n} \circ R_{T, u}.$$

Now $\{\lambda \mapsto R_{T_n, v}(\lambda)\}_{n \geq 0}$ is not normal on V , so λ is active. □

Main Theorem

For any integer $\Delta \geq 3$ the zero-locus, the activity-locus and the density-locus are equal and contained in the $\#\mathcal{P}$ -locus. In other words:

$$\overline{\mathcal{Z}}_{\Delta} = \mathcal{A}_{\Delta} = \overline{\mathcal{D}}_{\Delta} \subseteq \overline{\#\mathcal{P}}_{\Delta}.$$

Exponentially fast implementation

Lemma

Let $\Delta \geq 3$ be an integer. Let $\lambda_0 \in \mathcal{D}_\Delta \cap \mathbb{Q}[i]$. Then given $P \in \mathbb{Q}[i]$ and rational $\varepsilon > 0$ there exists an algorithm that generates a rooted tree (T, ν) such that $|R_{T, \nu}(\lambda_0) - P| \leq \varepsilon$ and $Z_{T, \nu}^{\text{out}}(\lambda_0) \neq 0$, and outputs $Z_{T, \nu}^{\text{in}}(\lambda_0)$ and $Z_{T, \nu}^{\text{out}}(\lambda_0)$ in time bounded by $\text{poly}(\text{size}(\varepsilon, P))$.

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Now in [Bez+20, Section 6] the authors show that a polynomial time algorithm to approximate $|Z_G(\lambda_0)|$ within a constant factor, combined with the Lemma above for λ_0 yields an algorithm that on input of a graph G of maximum degree at most Δ exactly computes $Z_G(1)$, the number of independent sets of G , in polynomial time in the number of vertices of G .

Remark

Instead of looking at the class of bounded degree graphs \mathcal{G}_Δ , you could look at other classes of graphs.

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Question

Is the region $\mathbb{C} \setminus \overline{\mathcal{Z}_\Delta}$ connected?

The end

Thank you for your attention!

Cayley trees

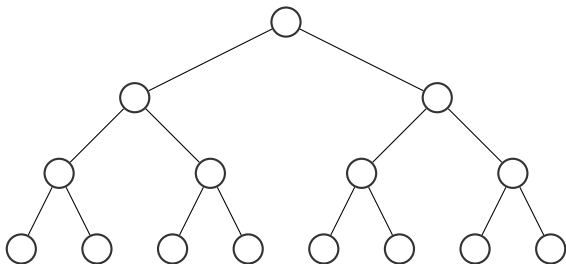


Figure: Cayley tree with down degree $d = 2$

Cayley trees

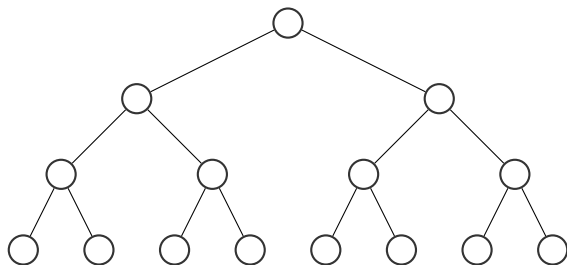
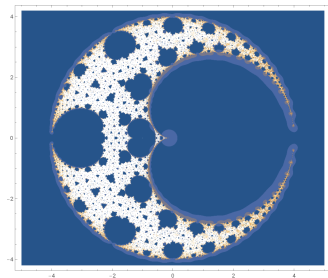


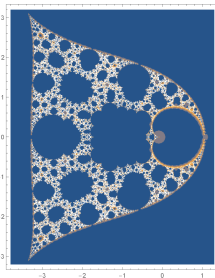
Figure: Cayley tree with down degree $d = 2$

Iteration of the map $f_{\lambda,d}(z) = \frac{\lambda}{(1+z)^d}$

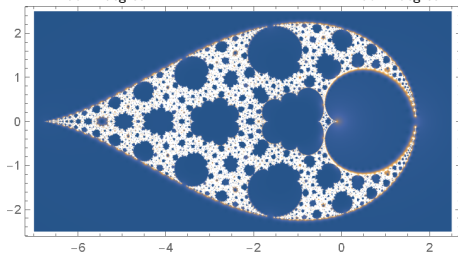
Activity locus Cayley trees



down-degree 2



down-degree 4



down-degree 3

Complexity of approximating $Z_G(\lambda)$

Let $\lambda \in \mathbb{Q}[i]$, $\Delta \in \mathbb{N}$ and consider the following computational problems.

Name #IndependenceNorm(λ, Δ, K)

Input A graph G of maximum degree at most Δ .

Output If $Z_G(\lambda) \neq 0$ the algorithm must output a rational number N such that $N/K \leq |Z_G(\lambda)| \leq KN$. If $Z_G(\lambda) = 0$ the algorithm may output any rational number.

Name #IndependenceArg(λ, Δ, ρ)

Input A graph G of maximum degree at most Δ .

Output If $Z_G(\lambda) \neq 0$ the algorithm must output a rational number A such that $|A - a| \leq \rho$ for some $a \in \arg(Z_G(\lambda))$. If $Z_G(\lambda) = 0$ the algorithm may output any rational number.

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For most $\lambda \in \mathbb{C}$ exact computation of $Z_G(\lambda)$ for large graphs is $\#P$ -hard.

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Computing $Z_G(1)$ exactly is $\#P$ -hard